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TITLE: VEHICLE HEADLAMP APPARATUS

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## VEHICLE HEADLAMP APPARATUS

[0001]

### BACKGROUND OF THE INVENTION

The present invention relates to a headlamp apparatus for  
5 vehicles such as automobiles for changing the direction of the  
light-emitting optical axis of a headlamp by making use of a  
motor as a drive source, and more particularly to a vehicle  
headlamp apparatus preferred for use for a headlamp apparatus  
comprising a light distribution control means, such as the  
10 Adaptive Front-lighting System (hereinafter, referred to as  
AFS), for changing the illuminating direction and range of the  
headlamp to follow the driving direction of a vehicle.

[0002]

As an AFS that has been proposed to enhance the driving  
15 safety of automobiles, U.S. Published Patent Application  
2002-0064051 A1 (published on May 30, 2002) describes a  
technology proposed by the inventor of this invention. As the  
concept of the technology is briefly shown in Fig. 1, in this  
AFS, information indicating the driving conditions of an  
20 automobile CAR is detected by a sensor 1, and what has been  
detected is outputted to an electronic control unit  
(hereinafter, referred to as ECU). As the sensor 1, there are  
provided, for example, a steering angle sensor 1A for detecting  
an angle through which a steering wheel SW of the automobile  
25 CAR is steered, a vehicle speed sensor 1B for detecting the

vehicle speed of the automobile CAR and vehicle height sensors 1C for detecting the respective heights of front and rear axles to detect the horizontality (level) of the automobile CAR (only a sensor for a rear axle is shown in Fig. 1), these sensors 1A, 5 1B and 1C being connected to the ECU. The ECU 2 controls swivel lamps 3R, 3L or headlamps 3 equipped at the front of the automobile on the right- and left-hand sides thereof, respectively, which are adapted for changing their light distributions by controlling the side-to-side change of the 10 illuminating direction of light based on outputs from the respective sensors 1. As the swivel lamps 3R, 3L, there is provided, for example, a headlamp in which a reflector and a projector lamp that are provided in the headlamp are constructed so as to rotate or swivel in horizontal directions and which 15 comprises a rotationally driving means for rotationally driving the reflector and the projector lamp by means of a drive source such as a driving motor. The mechanism including the rotationally driving means is referred to as an actuator herein. According to the AFS of this type, when the automobile is driven 20 on a curved road, the road surface ahead of a curve on the curved road can be illuminated according to the driving speed of the automobile, and thus, the AFS is effective when attempting to enhance the driving safety of the automobile.

[0003]

25 When there occurs in this AFS a defect that the direction

of the optical axis of the headlamp cannot be changed properly, that is, when there occurs a defect that the illuminating direction of the headlamp cannot be controlled with the illuminating direction of the headlamp being kept shifted  
5 either leftward or rightward relative to the straight-ahead running direction of the automobile, the foreground of the automobile cannot be illuminated when the automobile drives straight ahead or takes a turn at an opposite bend to the direction in which the reflector and the projector lamp are kept  
10 shifted, whereby the driving safety is deteriorated.

Alternatively, when there occurs a defect that the illuminating direction continues to change side to side, there may be caused a risk that drivers of oncoming vehicles and/or vehicles in the vicinity of the subject vehicle are dazzled and are then put  
15 to dangerous conditions. While the following cases are considered as reasons for triggering the defects: there occurs a certain defect in the sensors 1, and no outputs from the sensors 1 cannot be inputted into the ECU 2; there occurs a certain defect in the ECU 2; and there occurs a certain defect in the actuators  
20 of the respective swivel lamps 3R, 3L, most of the defects are triggered when a main control circuit such as a microcomputer incorporated in the ECU 2 or sub-control circuits integrally provided on the actuators of the respective swivel lamps 3R, 3L runs away.

25 [0004]

When the AFS fails due to the runaway of the main control circuit or the sub-control circuits, since the normal condition can be restored from the failing condition immediately the control circuits are reset, it is considered that a reset circuit is provided on the main control circuit and/or the sub-control circuits. In particular, in case an automatic reset circuit is provided for automatically implementing an automatic reset operation based on a signal which has detected a defect, the control circuit can be reset immediately the defect occurs so as to be recovered from the problematic condition. Since the main control circuit having the ECU 2 can be placed at an appropriate position on the vehicle, as shown in Fig. 1, and there is little limitation imposed on the external size and capacity of the ECU 2, it is relatively easy to incorporate the automatic reset circuit in the main control circuit. However, since the actuator having the sub-control circuit needs to be incorporated in the swivel lamp 3R, 3L, the external configuration and capacity of the actuator are subjected to a certain restriction, and therefore, it is difficult to provide the automatic reset circuit that is provided on the main control circuit on the sub-control circuit. Due to this, once a defect occurs, it becomes difficult to get recovered from a problematic condition quickly by automatically resetting the sub-control circuit.

25 [0005]

## SUMMARY OF THE INVENTION

An object of the invention is to provide a vehicle headlamp apparatus which enables an automatic reset of the sub-control circuit only by providing a simple power-on resetting circuit 5 on the sub-control circuit so that the AFS can get recovered from a problematic condition as quickly as possible.

[0006]

According to an aspect of the invention, there is proposed a vehicle headlamp apparatus having an optical axis direction 10 changing means for changing the direction of a light-emitting optical axis of a headlamp of a vehicle, the vehicle headlamp apparatus comprising a sub-control circuit provided integrally on the headlamp for controlling the optical axis direction changing means and a main control circuit for sending out to 15 the sub-control circuit a control signal for changing the direction of the optical axis of the headlamp, wherein the sub-control circuit comprises, in turn, a power-on resetting circuit for implementing a reset by switching on and off a power supply, and wherein the main control circuit comprises, in turn, 20 a power supply control means for temporarily cutting off the supply of power to the sub-control circuit when the main control circuit detects an abnormality of the sub-control circuit. In addition, the main control circuit makes the power supply control means to continue to maintain the power supply cut off 25 state when the main control circuit detects an abnormality in

the sub-control circuit again after the power supply control means has been activated.

[0007]

In the invention, the main control circuit sends out a  
5 request-a-reply signal to the sub-control circuit and activates the power supply control means when no appropriate reply signal to the request-a-reply signal is sent back from the sub-control circuit. Alternatively, the main control circuit activates the power supply control means when a reply signal is sent  
10 thereto from the sub-control circuit to which no request-a-reply signal has been sent out therefrom.

[0008]

According to the invention, with the power-on resetting circuit of a simple construction comprising a capacitor and a  
15 resistor being provided on the sub-control circuit, when the main control circuit detects an abnormality in the sub-control circuit, in the event that the supply of power to the sub-control circuit is cut off once by the power supply control means, the sub-control circuit can be reset by the power-on resetting  
20 circuit, so that the abnormality triggered due to the runaway of the sub-control circuit can be resolved, and the AFS is allowed to get recovered as quickly as possible from a problematic condition triggered by the abnormality of the sub-control circuit.

25 [0009]

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a drawing illustrating the concept of an AFS;

Fig. 2 is a vertical sectional view of a swivel lamp;

Fig. 3 is an exploded perspective view of a main part of  
5 an internal construction of the swivel lamp;

Fig. 4 is a partial exploded perspective view of the  
actuator;

Fig. 5 is a plan view illustrating the construction of  
the actuator;

10 Fig. 6 is a longitudinal sectional view of the actuator;

Fig. 7 is a block diagram illustrating a circuit  
configuration of the AFS;

Fig. 8 is a circuit diagram illustrating the circuit  
configuration of the actuator;

15 Figs. 9A to 9C are timing charts of sending and receiving  
signals to detect an abnormality in the actuator;

Fig. 10 is a flowchart illustrating operations executed  
at a normal time and when a first abnormality occurs; and

Fig. 11 is a flowchart illustrating operations executed  
20 at a normal time and when a second abnormality occurs.

[0010]

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Next, an embodiment of the invention will be described  
by reference to the accompanying drawings. Fig. 2 is a vertical  
25 view of an internal construction of a headlamp comprising, among

the constituent elements of the AFS shown as a lamp angle change control means in Fig. 1, the swivel lamp which can change the illuminating direction thereof side to side, and Fig. 3 is a partially exploded perspective view of a main part of the swivel  
5 lamp. A lens 12 is mounted in a front opening and a rear cover 13 is mounted in a rear opening in a lamp body 11, respectively, whereby a lamp chamber 14 is formed, and a projector lamp 30 is disposed in the lamp chamber 14. The projector lamp 30 includes a sleeve 301, a reflector 302, a lens 303 and a light source 304 which are integrated into a single unit, and since  
10 the project lamp so constructed has already been in wide use, a detailed description thereof will be omitted here only with a single remark that a light source employing a discharge bulb is used for the light source 304. The projector lamp 30 is  
15 supported on a substantially U-shaped bracket 31. In addition, an extension 15 is disposed around the periphery of the projector lamp 30 in the lamp body 11 so that the interior of the lamp body 11 is not exposed to the outside through the lens 12. Furthermore, in this embodiment, a bottom cover mounted  
20 in a bottom opening in the lamp body 11 is utilized in installing therein an illuminating circuit 7 for illuminating the discharge bulb of the projector lamp 30.

[0011]

The projector lamp 30 is supported in a state in which  
25 the projector lamp 30 is held between a lower plate 312 and an

upper plate 313 which are both formed by being bent substantially at right angles from a vertical plate 311 of the bracket 31. An actuator 4, which will be described later on, is fixed to a lower side of the lower plate 312 with screws, 5 and a rotational output shaft 448 of the actuator 4 protrudes upwardly through a shaft hole 315 opened in the lower plate 312. The screws 314 are fixedly screwed into bosses 318 provided on the lower side of the lower plate 312 in such a manner as to protrude therefrom. Then, a shaft portion 305 provided on an 10 upper surface of the projector lamp 30 is fitted in a bearing portion 316 provided on the upper plate 313, and a connecting portion 306 provided on a lower surface of the projector lamp 30 is fitted on the rotational output shaft 448 of the actuator 4 for connection, whereby the projector lamp 30 is allowed to 15 rotate in leftward and rightward directions relative to the bracket 31, and, as will be described later on, is designed to be operated to rotate in horizontal directions together with the rotational output shaft 448 as the actuator 4 operates.

[0012]

20 Here, as viewed from the front, aiming nuts 321, 322 are integrally mounted on the bracket 31 at top left- and right-hand side corner portions thereof, and a leveling bearing portion 323 is integrally mounted on a bottom right-hand side corner portion, so that a horizontal aiming screw 331 and a vertical 25 aiming screw 332 which are rotatably supported on the lamp body

11 are screwed into the aiming nuts 321, 322, respectively, and a leveling pole 51 of a living mechanism 5 is fitted in the leveling bearing portion 323. Then, by operating the horizontal aiming screw 331 and the vertical aiming screw 332 5 to rotate, the bracket 31 is allowed to rotate horizontally and vertically. In addition, by moving the leveling pole 51 axially back and forth by the leveling mechanism 5, the bracket 31 is allowed to rotate vertically. Thus, an aiming adjustment and a leveling adjustment are enabled through these operations, the 10 aiming adjustment being intended to adjust the optical axis of the projector lamp 30 horizontally and vertically and a leveling adjustment to adjust the optical axis of the projector lamp 30 vertically according to the leveling conditions of a vehicle which change in association with a change in vehicle height.

15 In addition, a projection 307 is provided on a lower side of the reflector 302 of the projector lamp 30 in such a manner as to protrude therefrom, and a pair of stoppers are cut and erected from the lower plate 312 of the bracket 31 at left- and right-hand side positions thereon which correspond to the projection so 20 provided, so that the rotational range of the projector lamp 30 is restricted when the projection 307 is brought into collision contact with either of the stoppers 317 as the projector lamp 30 rotates.

[0013]

25 Fig. 4 is an exploded perspective view of a main part of

the actuator 4 for swiveling the swivel lamp 3R, 3L, Fig. 5 is a plan view showing the construction of the actuator assembled together, and Fig. 6 is a longitudinal sectional view of the assembled actuator. A case 41 is made up of an upper half 41U 5 and a lower half 41D which are each formed into a substantially pentagonal disc-like shape, and when a plurality of projections 410 provided on a circumferential surface of the lower half 41D in such a manner as to protrude therefrom and a plurality of fitting pieces 411 provided on a circumferential surface of the 10 upper half 41U in such a manner as to suspend downwardly therefrom are brought into fit engagement with each other, a case chamber is formed inside the upper half 41U and the lower half 41D so fitted together. In addition, supporting pieces 412, 413 are formed on sides of the upper half 41U and the lower 15 half 41D in such a manner as to protrude horizontally outwardly therefrom for use in fixing the case 41 to the bracket 31 by screwing the screws 314 into the bosses 318 on the bracket 31 through the supporting pieces 412, 413 as has been described before. In addition, the splined rotational shaft 448 is caused 20 to protrude from an upper surface of the case 41 for connection to the connecting portion 306 formed on the bottom surface of the projector lamp 30. Additionally, a connector 451 is disposed on a back of the case 41 so that an external connector 21 (refer to Fig. 2) which is connected to the ECU 2 is designed 25 to be connected thereto.

[0014]

Four hollow bosses 414, 415, 416, 417 are provided on an inner bottom surface of the case 41 at predetermined positions in such a manner as to erect therefrom, and a brushless motor 5 42, which will be described later on, is assembled onto the first hollow boss 414 as a drive motor. In addition, as will be described later on, respective shafts of a gear mechanism 44 are inserted into the second to fourth hollow bosses 415, 516, 417 to be supported therein. Additionally, a printed circuit 10 board 45 is placed on a staged rib 418 formed along a circumferential edge of the inner bottom surface of the lower half 41D and is installed to be supported within the case 41 while being held between the upper half 41U and the lower half 41D. The brushless motor 42 is electrically connected to this 15 printed circuit board 45, and various types of electronic components, not shown, which function as part of a control circuit 43, which will be described later on, and the connector 451 are installed on the printed circuit board 45.

[0015]

20 As shown in Fig. 6, the brushless motor 42 is constructed such that a stator coil 424 including three pairs of coils which are disposed at regular intervals in a circumferential direction is fixedly supported on the first hollow boss 414 on the lower half 41D and is then electrically connected to the 25 printed circuit board 45 so as to be fed. In addition, a

cylindrical container-like rotor 426 is fixedly mounted on an upper end portion of a rotational shaft 423 which is rotatably supported on the first hollow boss 414 by a thrust bearing 421 and a sleeve bearing 422 in such a manner as to cover the stator 5 coil 424. This rotor 426 includes a cylindrical container-like yoke 427 formed from a resin and an annular rotor magnet 428 which is fixedly mounted on an inner circumferential surface of the yoke 427 and which is magnetized in such a manner that S and N poles alternate in a circumferential.

10 [0016]

The brushless motor 42 constructed as has been described above is designed to change the direction of a magnetic force between the stator coil 424 and the rotor magnet 428 by supplying alternating currents having U, V and W phases which are 15 different from one another to thereby drive to rotate the rotor 426 and the rotational shaft 423. Furthermore, as shown in Fig. 7, three Hall elements H1, H2, H3 are arranged and supported on the printed circuit board 45 at predetermined angular intervals in a circumferential direction of the rotor 426, and 20 when the rotor magnet 428 is rotated together with the rotor 426, magnetic fields in the respective Hall elements H1, H2, H3 are changed, and on and off conditions of the respective Hall elements H1, H2, H3 are then changed, whereby a pulse signal is designed to be outputted in which an H level and an L level 25 are changed periodically in response to the rotational cycle

of the rotor 426.

[0017]

A first gear wheel 441 is integrally formed on the yoke 427 of the rotor 426 from a resin, and this first gear wheel 441 constitutes part of the gear mechanism 44. The gear mechanism 44 transmits the rotational force of the first gear wheel 441, while sequentially decelerating it, to a second large-diameter gear wheel 443a and a second small-diameter gear wheel 443b of a second gear wheel 443 rotatably supported on 10 a first stationary shaft 442, a third large-diameter gear wheel 445a and a small-diameter gear wheel 445b of a third gear wheel 445 rotatably supported on a stationary shaft 444 and a sector gear wheel 447 integrally formed on the rotational output shaft 448 and which is rotatably supported on a third stationary shaft 15 446. In addition, stoppers 419 are formed on the inner bottom surface of the lower half 41D at positions thereon corresponding to both ends of rotational directions of the sector gear wheel 447 in such a manner as to protrude therefrom for collision contact with respective end portions of the sector gear wheel 20 447 so as to restrict the total rotational angle range of the sector gear wheel 447 or the rotational output shaft 448. Note that the total rotational angle range of the sector gear wheel 447 is set to become slightly larger than the total rotational angle range of the projector lamp 30 that is restricted by the 25 projection 307 and the stoppers 317.

[0018]

Fig. 7 is a block diagram showing an electric circuit configuration of an illumination system including the ECU 2 and the actuator 4. Note that the actuator 4 is installed in each 5 of the left and right swivel lamps 3R, 3L of the automobile and is allowed to communicate with the ECU 2 bilaterally. The ECU 2 includes a main CPU 201 as a main control circuit for implementing a process with a predetermined algorithm based on information from the sensors 1 so as to output a required control 10 signal C0 and an interface (hereinafter, referred to as I/F) circuit 202 for inputting and outputting the control signal C0 between the main CPU 201 and the actuator 4. As will be described later on, here, the control signal C0 has a left and right direction change angle signal DS indicating optical axes 15 direction change angles of the swivel lamps 3R, 3L which is sent to the actuators 4 and a request-a-replay signal RS for detecting a defect. The main CPU 201 has therein an abnormality detecting unit 203 for detecting a defect using a programmed software and, as will be described later on, detects a defect 20 according to a reply condition from a sub-CPU 431. In addition, an automatic reset circuit 204 is additionally provided in the main CPU 201 so that the main CPU 201 can automatically be reset. Furthermore, a power supply control circuit 205 is provided in the ECU 2, so that power supplied to the actuator 4 can be cut 25 off temporarily or continuously through the control by the main

CPU 201. In addition, on and off signals from a lighting switch S1 provided on the automobile can be inputted into the ECU 2, so that the swivel lamp 3R, 3L can be switched between on and off by controlling based on the on and off of the lighting switch 5 S1 the illuminating circuit 7 for supplying power to the discharge bulb 304 of the projector lamp 30 when connected to an on-board power supply, not shown, by a control signal N. Additionally, the main CPU 201 controls by a leveling signal DK a leveling control circuit 6 for controlling the leveling 10 mechanism 5 for vertically adjusting the optical axis of the bracket 31 which supports the projector lamp 30, so that the optical axis of the projector lamp 30 can be adjusted as the height of the automobile changes. Note that it goes without saying that connections of these electric circuits to the power 15 supply are switched on and off by an ignition switch S2 for switching on and off electric systems provided on the automobile.

[0019]

The sub-control circuit 43 configured on the printed 20 circuit board 45 installed within the actuator 4 provided in each of the swivel lamps 3R, 3L includes an I/F circuit 432 for inputting and outputting signals from and to the ECU 2, a sub-CPU 431 for implementing a process with a predetermined algorithm based on a signal inputted from the I/F circuit 432 and pulse 25 signals P outputted from the Hall elements H1, H2, H3 and a motor

drive circuit 434 for rotationally driving the brushless motor 42 which functions as a rotationally driving means. A power-on resetting circuit 437 to which an onboard power supply is supplied via the power supply control circuit 205 of the ECU 5 2 is additionally provided in the sub-CPU 431, so that the sub-CPU 431 is reset when the power supply to the power-on resetting circuit 437 is cut off. Although not shown, since it can be made up of a capacitor and a resistor, the power-on resetting circuit is, in reality, integrally assembled onto the 10 printed circuit board 45 which configures the sub-control circuit 43. In addition, the sub-CPU 431 is configured so as to send out to the ECU 2 an operating condition signal JS which indicates the operating condition of the sub-CPU 431.

[0020]

15 Fig. 8 is a circuit diagram typically showing the motor drive circuit 434 of the control circuit 43 and the brushless motor 42 in the actuator 4. The motor drive circuit 434 includes a switching matrix circuit 435 to which a speed control signal V, start/stop signal S, forward rotation/backward rotation 20 signal R are inputted from the sub-CPU 431 of the control circuit 43 as control signals and pulse signals are inputted from the three Hall elements H1, H2, H3, and an output circuit 436 for adjusting phases of powers in three phases (U phase, V phase, W phase) supplied to the three pairs of coils of the stator coil 25 424 of the brushless motor 42 when receiving an output from the

switching matrix circuit 435. In this motor drive circuit 435, by supplying powers in U phase, V phase and W phase to the stator coil 424, the magnet rotor 428 rotates, and then, the yoke 427 which is made integral with the magnet rotor 428, that is, the 5 rotor 426 and the rotational shaft 423 rotate. When the magnet rotor 428 rotates, the Hall elements H1, H2, H3 detect changes in magnetic field and output pulse signals P, which are then inputted into the switching matrix circuit 435, where a switching operation at the output circuit 436 is implemented 10 to the timings of the pulse signals, whereby the rotor 426 is allowed to continue rotating.

[0021]

According to the configuration as has been described heretofore, with the ignition switch S2 on and also the lighting 15 switch S1 on, as shown in Fig. 1, when information on an angle through which the steering wheel SW of the automobile is steered, the speed of the automobile and the height of the automobile is inputted into the ECU 2 from the sensors 1, the ECU 2 implements an operation at the main CPU 201 based on the sensor 20 outputs which have been inputted into the ECU 2, calculates a left and right direction change angle signal DS of the projector lamp 30 in each of the swivel lamps 3R, 3L of the automobile and outputs the left and right direction change angle signal DS so calculated to the actuator 4 in each of the respective 25 swivel lamps 3R, 3L. In the actuator 4, the sub-CPU 431

implements an operation by the left and right direction change angle signal DS so inputted into the actuator 4 to calculate a signal corresponding to the left and right direction change angle signal DS and then outputs the signal so calculated to 5 the motor drive circuit 434 to thereby rotationally drive the brushless motor 42. Since the rotational driving force of the brushless motor 42 is decelerated by the gear mechanism 44 for transmission to the rotational output shaft 448, the projector lamp 30 connected to the rotational output shaft 448 rotates 10 horizontally, and the direction of the optical axis of the swivel lamp 3R, 3L is changed horizontally. When the projector lamp 30 rotates, the direction change angle of the projector lamp 30 is detected from the rotation angle of the brushless motor 42. Then, the sub-CPU 431 compares the direction change 15 angle detection signal so detected with the left and right direction change angle signal DS inputted from the ECU 2 and feedback controls the rotation angle of the brushless motor 2 in such a manner that the two signals coincide with each other, so that the direction of the optical axis of the projector lamp 20 30, that is, the direction of the optical axis of the swivel lamp 3R, 3L can be controlled with high accuracy to be situated at a direction change position which is set by the left and right direction change angle signal DS.

[0022]

25 Thus, through the direction changing operation on the

projector lamps 30, the directions of the axes of beams of light emitted from the both swivel lamps 3R, 3L are changed and the beams of light whose directions are so changed illuminate areas which are horizontally out of the straight-ahead running 5 direction of the automobile, whereby not only the foreground straight-ahead of the moving automobile but also the foreground in a direction in which the automobile is steered can be illuminated, thereby making it possible to enhance the driving safety of the automobile.

10 [0023]

Next, operations of the vehicle headlamp apparatus when a defect occurs in the ECU 2 and the actuator 4 will be described below. As to the ECU 2, the main CPU 201 monitors its own operating conditions at all times, and when the ECU 2 detects 15 an abnormality therein, the ECU 2 resets itself by the automatic reset circuit 204, whereby, for example, in the event that an abnormal signal is inputted from the sensors 1 and the actuator 4 to make the main CPU 201 run away, a reset is applied immediately and the ECU 2 can be restored to its normal 20 condition.

[0024]

On the other hand, a case where an abnormality occurs in the actuator 4 will be described below. Fig. 9A is a timing chart when signals are sent and received at the normal time. 25 In addition, Fig. 10 is a flowchart illustrating a flow of

detecting an abnormality, as well as a flow of operations taken to deal with the abnormality so detected. In these diagrams, the main CPU 201 sends out the left and right direction change angle signal DS to the sub-CPU 431 in each actuator 4 in each 5 swivel lamp 3R, 3L on a predetermined cycle and sends out a request-a-replay signal RS to one and the other actuator alternately. For example, in the same figure, firstly, a reply requesting signal RS is sent to the right swivel lamp 3R in time series (S101). Then, keep queuing for a predetermined length 10 of time and wait until an operating condition signal JS is received from the actuator 4 (S102). When an operating condition signal JS indicating the operating condition of the actuator 4 is sent back from the sub-CPU 431 while queuing, the main CPU 201 receives this operating condition signal JS (S103). 15 The abnormality detecting unit 203 within the main CPU 201 determines that the operating condition of the actuator 4 is normal from the fact that the operating condition signal JS has been received properly (S105), and thereafter, realizes a proper and normal optical axis direction changing operation 20 (S106). Similarly, next, a reply requesting signal RS is sent to the sub-CPU 431 in the left swivel lamp 3L and realizes a proper optical axis direction changing operation when receiving a return of an operating condition signal JS.

[0025]

25 Incidentally, in the event that there occurs a defect in

the actuator 4, whereby the sub-CPU 431 is brought to a runaway state, as has been described previously, the proper control of the AFS becomes impossible. In this case, the runaway of the sub-CPU 431 is stopped in the following manner. Fig. 9B is a

5 timing chart of sending and receiving signals when a first abnormality occurs. Referring to the flowchart shown in Fig.

10 again, similarly to when it is normal, the main CPU 201 sends out the left and right direction change angle signal DS to the sub-CPUs 431 of the actuators 4 in the left and right swivel

10 lamps 3R, 3L on the predetermined cycle and also sends out a request-a-reply signal RS to one and the other actuator alternately (S101). In the same figure, the request-a-reply signal RS is first sent to the right swivel lamp 3R in time series.

Then, the main CPU 201 queues a predetermined length of time

15 (S102), and if no operating condition signal JS indicating the condition of the actuator 4 is sent back from the sub-CPU 431 while the main CPU 201 is queuing and hence the main CPU 201 can receive no operating condition signal JS (S103), the main CPU 201 then detects that the sub-CPU 431 is running away and

20 hence that the actuator 4 is abnormal (S107). Then, when detecting the abnormality, the main CPU 201 controls the power supply control means 205 to cut off the power supply supplied to the actuator 4 temporarily (S108), whereby the power-on resetting circuit 437 is activated in the actuator 4 in question

25 so as to reset the sub-CPU 431 (S109). The runaway of the

sub-CPU 431 is stopped by this reset. The same operation is carried out to the left swivel lamp 3L. Thus, the actuator 4 is brought back to the normal operation by resetting the sub-CPU 431 in that manner, and thereafter, the actuator 4 realizes a proper optical axis direction changing operation by signals DS, RS from the main CPU 201.

[0026]

In addition, despite the fact that the sub-CPU 431 has been reset by carrying out the runaway stopping operation as 10 has just been described, if the abnormality of the actuator 4 continues to be detected by the abnormality detecting unit 203 of the main CPU 201 (S110), the main CPU 201 determines that the abnormality is not being caused by the runaway of the sub-CPU 431, in which case the power supply control circuit 205 is made 15 to continue cutting off the power supply to the power-on resetting circuit 437 (S111), whereby the sub-CPU 431 is activated in no case, and the optical axis direction changing operation by the actuator 4 is stopped. As this occurs, a fail safe is executed in the actuator 4 in which the optical axis 20 is reset to the initial position (S112), whereby the continuation of the abnormal condition of the AFS can be prevented.

[0027]

Fig. 9C is a timing chart of sending and receiving signals 25 when a second abnormality occurs. Here, referring to a

flowchart shown in Fig. 11, there is described, for example, a case where only a left and right direction change angle signal DS is sent out and no request-a-reply signal RS is sent out. Thus, despite the fact that no request-a-reply signal RS is sent 5 out (S101), in case an operating condition signal JS indicating the condition of the actuator 4 is sent back from the sub-CPU 431 within the predetermined cycle time and the main CPU 201 receives the operating condition signal JS (S102, S104), the main CPU 201 detects that the relevant sub-CPU 431 is running 10 away and hence that the actuator 4 is abnormal (S107). In contrast, if no operating condition signal JS is received, then, the main CPU 201 determines that the actuator 4 is normal, whereby a normal optical axis direction changing operation is carried out (S106). Then, when the main CPU 201 detects an 15 abnormality in the actuator 4, as with the case of the first abnormality, the main CPU 201 controls the power supply control means 205 to cut off the power supply being supplied to the actuator 4 temporarily (S108), whereby the power-on resetting circuit 437 is activated in the actuator 4 in question to thereby 20 reset the sub-CPU 431 (S109). The sub-CPU 431 is prevented from running away by this reset. By resetting the sub-CPU 431 like this, the actuator 4 is brought back to the normal operation, and thereafter, the actuator 4 realizes a normal optical axis direction changing operation by signals DS, RS sent from the 25 main CPU 201.

[0028]

Note that also in the case of the second abnormality, if the main CPU 201 continues to detect the abnormality of the actuator 4 despite of the fact that the sub-CPU 431 has been 5 reset (S110), as with the case of the first abnormality, the power supply control circuit 205 is caused to continue cutting off the power supply to the power-on resetting circuit 437 (S111) so that the sub-CPU 431 is not activated, and a fail safe is then executed (S112).

10 [0029]

In addition, although not shown, in the case of the second abnormality, for example, if no operating condition signal JS is sent back from the actuator 4 of the right swivel lamp 3R in question but from the actuator 4 of the left swivel lamp 3L 15 despite the fact that the main CPU 201 sends out a request-a-reply signal RS to the actuator 4 of the right swivel lamp 3R, a similar determination is made. That is, in this case, since both the left and right actuators 4 can be determined to be running away, the main CPU 201 may only have to temporarily 20 cut off the power supply to both the left and right actuators 431 to thereby execute power-on resetting operations.

[0030]

Thus, in the sub-CPU 431 provided in the actuator 4, the sub-control circuit 43 may only have to be configured by 25 installing the power-on resetting circuit 437 of a simple

configuration comprising a capacitor and a resistor on the printed circuit board 45, whereby even in the limited space within the actuator 4, an environment can be arranged in which the sub-CPU 431 can be reset. Then, the runaway of the sub-CPU  
5 431 in the actuator 4 is detected by the CPU 201 of the ECU 2, and based on this detection, the power supply to the actuator 4 is temporarily cut off by the power supply control circuit 205 provided in the ECU 2, whereby the runaway of the sub-CPU 431 can be stopped by resetting the sub-CPU 431 in a similar  
10 manner to a reset by an automatic resetting circuit. Consequently, a defect in the AFS can be removed as quickly as possible so as to restore the normal condition therein, whereby a safe optical axis direction changing control can be ensured.

[0031]

15 Note that while the example has been described in the embodiment in which the invention is applied to the headlamp in which the direction of the projector lamp constituting the swivel lamp is horizontally changed to thereby change the light-emitting optical axis thereof, the invention may be  
20 applied to a headlamp configuration in which only a reflector is operated so as to change the direction thereof or a headlamp configuration in which an auxiliary reflector provided independently from a main reflector is operated so as to change the direction thereof to thereby change the substantial  
25 illuminating range of the headlamp.

[0032]

As has been described heretofore, according to the invention, with the power-on resetting circuit of a simple configuration comprising a capacitor and a resistor being provided in the sub-control circuit provided in the actuator, when the main control circuit detects an abnormality in the sub-control circuit, in the event that the power supply to the sub-control circuit is temporarily cut off by the power supply control means, the sub-control circuit can be reset by the power-on resetting circuit, whereby the abnormality triggered by the runaway of the sub-control circuit can be resolved so that the sub-control circuit can be restored to the normal condition. From this configuration, even in the event that there is not too sufficient a space for the actuator, the sub-control circuit can be restored to the normal condition from the abnormal condition by resetting it, thereby making it possible to allow the AFS to get recovered from the defect condition as quickly as possible.